
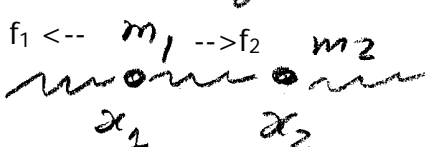
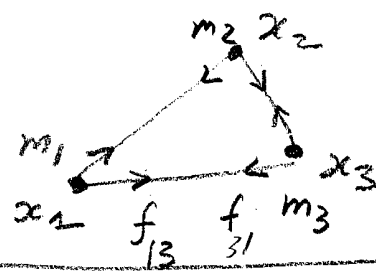


I. Finite - Da) oscillators: b) coupled: c) gravitational n-body: ① 2nd order ODE/ODSa) $m\ddot{x} = f(x, \dot{x}, \dots)$; $l\ddot{\theta} = -g \sin \theta$ b) $\begin{cases} m_i \ddot{x}_i = f_i \\ f_i = \begin{cases} -f_i + f_{i+1} \\ \sum_{j \neq i} f_{ij} \end{cases} \end{cases}$ (b) (c)

$$f_{ij} = f_{ji}(x_i - x_j)$$

Vector form: $M\ddot{X} = F(X, \dots)$ mass/inertia matrix/tensor $M = \begin{bmatrix} m_1 & 0 \\ 0 & m_n \end{bmatrix}$ ② Potential forces: $f_i = -\partial_i U$; $F = -\nabla U$ - pot. energya) $f = -kx$; $U = \frac{kx^2}{2}$; $f = -g \sin \theta \Rightarrow U = -g \cos \theta$ b) $f_i = -k_i(x_i - x_{i-1}) \Rightarrow U = \frac{1}{2} \sum_i k_i (x_i - x_{i-1})^2$

c) $f_{ij} = \frac{G m_i m_j}{r_{ij}^3} (x_i - x_j); \quad r_{ij} = |x_i - x_j|$

$\Rightarrow \boxed{U = - \sum_{i \neq j} \frac{G m_i m_j}{r_{ij}}}$ grav. potential

③ Energy conservation:

Kinetic: $K = \frac{1}{2} \sum m_i v_i^2; \quad v_i = \dot{x}_i$

Potential: $P = U(x_1, \dots, x_n)$

Total: $E = K + P = \text{const} \quad \boxed{\frac{d}{dt} E = 0}$

④ Hamiltonian formalism

Momenta: $p_i = m_i \dot{x}_i; \quad \text{Ham. f-n: } h(x, p) = \frac{1}{2} \sum \frac{p_i^2}{m_i} + U$

(Ham) $\begin{cases} \dot{x}_i = \frac{\partial h}{\partial p_i} \\ \dot{p}_i = -\frac{\partial h}{\partial x_i} \end{cases} \iff \begin{cases} m_i \ddot{x}_i = f_i \quad (\text{Newton}) \\ \dots \end{cases}$

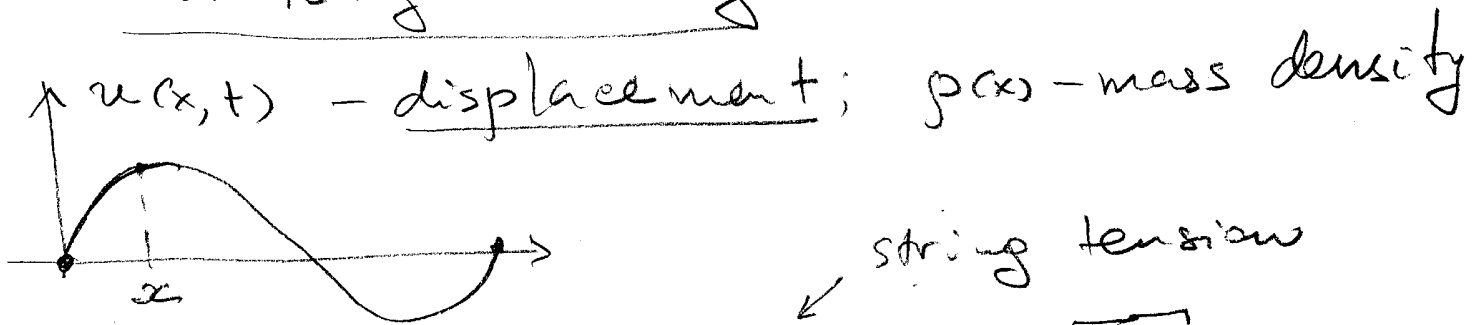
⑤ For 1D systems a), b) etc. energy cons. reduce 2nd order Newton to 1st order

$\boxed{m \ddot{x} = -U'(x)} \implies \frac{m \dot{x}^2}{2} + U(x) = E = \text{const} \implies$

$\boxed{\dot{x} = \pm \sqrt{\frac{2}{m} (E - U(x))}}$ \xleftarrow{x} 1st order separable ODE
 $\int_{x_0}^x \frac{dx}{\sqrt{\frac{2}{m} (E - U(x))}} = t - t_0$

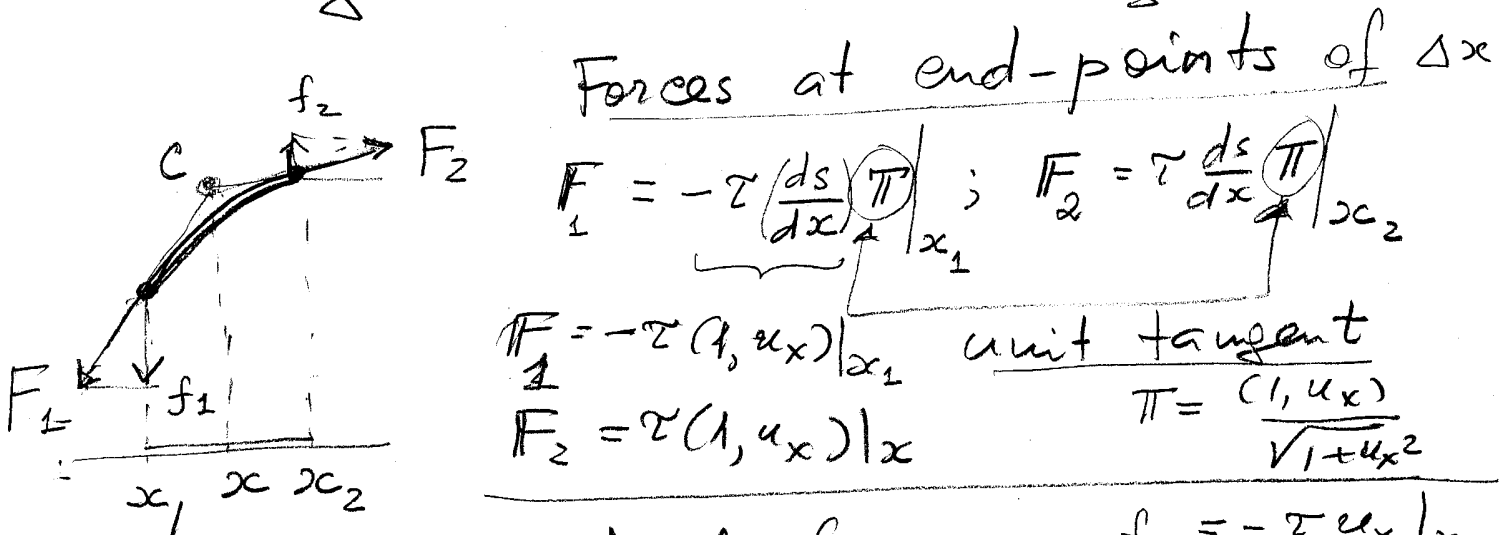
II. Continuous (∞ -D) systems

1. Vibrating string



Restoring force = $\tau ds = \tau \sqrt{1+u_x^2} dx$

\nwarrow string tension
 \nwarrow arc length



Vertical forces:

$$f_1 = -\tau u_x \Big|_{x_1}$$

$$f_2 = \tau u_x \Big|_{x_2}$$

Acceleration of approximate center-mass
 \approx acceleration of arc ???

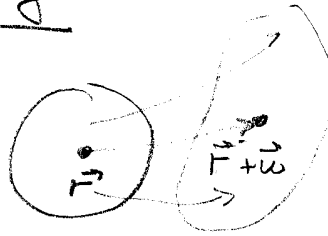
$$\int_{x_1}^{x_2} \rho u_{tt} dx \approx f_2 - f_1 = \tau u_x \Big|_{x_1}^{x_2} = \int_{x_1}^{x_2} \partial_x (\tau u_x) dx$$

$$\Rightarrow \boxed{\rho u_{tt} \approx (\tau u_x)_x} \quad \text{or} \quad \boxed{u_{tt} = c^2 u_{xx}}$$

with speed $c = \sqrt{\tau/\rho}$

Q: is \approx valid?

* Deformation:



$$\vec{r} \rightarrow \vec{r} + \vec{u}(\vec{r}, t)$$

Infinite deformation:

$$\vec{u}(\vec{r} + \Delta\vec{r}) \approx \underbrace{\vec{u}(\vec{r})}_{\text{shift}} + \underbrace{\left(\frac{\partial u_i}{\partial r_j}\right) \Delta\vec{r}}_{\text{lin. deform. tensor}}$$

* Strain tensor:

$$\epsilon_{ij} = \frac{\partial_i u_j + \partial_j u_i}{2} \quad \text{— symmetrized deform. tensor}$$

* $\sigma_{ij} = \phi_{ij}(s)$

— stress tensor (surface forces due to deformation)



$$\frac{d}{dt} \left(\int_D \rho \vec{u} \right) dV = \oint_{\Gamma} \sigma \cdot N dS \quad \text{Newton's}$$

$$\int_D \rho \frac{d^2 u_i}{dt^2} dV = \oint_{\Gamma} \sum_j \sigma_{ij} N_j dS = - \int_D \sum_j \partial_j (\sigma_{ij}) dV$$

$$\Rightarrow \rho \frac{d^2 u_i}{dt^2} = - \sum_j \partial_j \sigma_{ij} \left(\frac{\partial \vec{u}}{\partial r} \right) \quad \text{elastic moduli}$$

* Linear elasticity (Hooke): $\sigma_{ij} = \sum_{k,p} \phi_{ijkp} s_{kp}$

* Rotation symmetry (Cauchy): $\sigma_{ij} = \lambda \text{tr} S \delta_{ij} + 2\mu S_{ij}$
 λ, μ — Lamé coefficients.

$$\begin{bmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \dots \\ \dots & \dots \end{bmatrix} = \lambda (\nabla \cdot \vec{u}) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} + \mu \begin{bmatrix} 2\partial_1 u_1 & (\partial_1 u_2 + \partial_2 u_1) & \dots \\ \dots & \dots & \dots \\ \dots & \dots & \dots \end{bmatrix}$$

PDE system:

$$\rho \partial_t^2 u_i = \lambda \partial_i \nabla \cdot \vec{u} + \mu (\partial_i \nabla \cdot \vec{u} + \nabla^2 u_i)$$

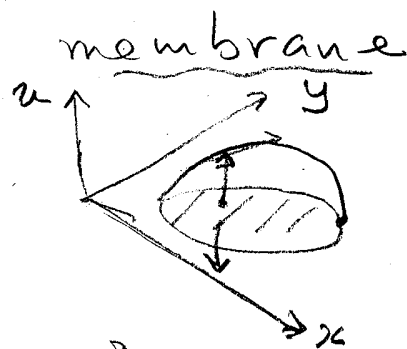
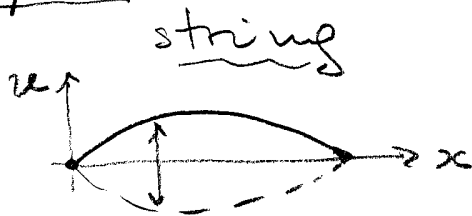
Vector form:

$$\boxed{\rho \vec{u}_{tt} = (\lambda + \mu) \nabla (\nabla \cdot \vec{u}) + \mu \nabla^2 \vec{u}} \quad (*)$$

Coordinate form (2D):

$$\rho \partial_t^2 \begin{pmatrix} u \\ v \end{pmatrix} = \begin{bmatrix} (\lambda + 2\mu) \partial_x^2 + \mu \partial_x^2 & (\lambda + \mu) \partial_{xy}^2 \\ (\lambda + \mu) \partial_{xy}^2 & \mu \partial_x^2 + (\lambda + 2\mu) \partial_y^2 \end{bmatrix} \begin{pmatrix} u \\ v \end{pmatrix}$$

Example 1:



Transverse
displacement:

$$\vec{u} = (0, u(x, t))$$

$$\vec{u} = (0, 0, u(x, y, t))$$

$$\boxed{\nabla \cdot \vec{u} = 0}$$

$$\boxed{\rho u_{tt} = \mu u_{xx}}$$

$$\boxed{\rho u_{tt} = \mu \nabla^2 u}$$

Wave eq-ns with speed $c = \sqrt{\mu/\rho}$

Helmholtz decomposition

(3)

$$\vec{w} = \underbrace{\nabla\phi}_{\text{irrotational}} + \underbrace{\nabla\times\vec{\psi}}_{\text{solenoidal}}$$

gives after substitution in (*) two scalar wave eq-ns with different speed

$$\underbrace{\nabla(\rho\phi_{tt} - (\lambda+2\mu)\nabla^2\phi)}_0 + \nabla\times(\underbrace{\rho\vec{\psi}_{tt} - \mu\nabla^2\vec{\psi}}_0) = 0$$

Potential field $\vec{w} = \nabla\phi$ propagates at speed $c_p = \sqrt{\frac{\lambda+2\mu}{\rho}}$ Compression waves

Solenoidal - " - $\vec{w} = \nabla\times\vec{\psi}$ - " - $c_s = \sqrt{\mu/\rho}$ Shear waves

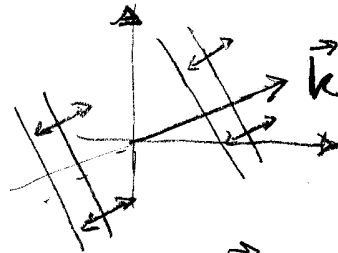
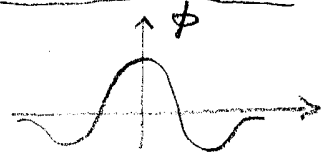
Example 2:

i) Compression (longitudinal) plane-wave:

$$\vec{w} = \nabla[\phi(\vec{k}\cdot\vec{x})] = \vec{k}\phi'(\vec{k}\cdot\vec{x})$$

\vec{k} - wave vector

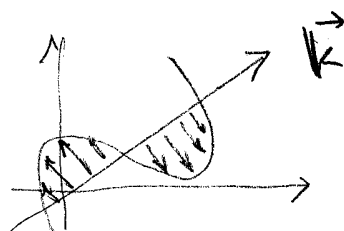
speed = c_p



ii) Solenoidal (shear) wave: $\vec{w} = \nabla\times[\vec{a}\times\vec{k}\psi(\vec{k}\cdot\vec{x})]$

$$\vec{w} = k^2 \vec{a} \psi'(\vec{k}\cdot\vec{x})$$

speed = $c_s < c_p$



(string & membrane are shear waves)

Maxwell eq-ns of electrodynamics

(3)

(I) Vacuum: E - electric f.; B - magnetic induction

I $\nabla \cdot B = 0$ - no magn. sources

II $\nabla \times E + \frac{1}{c} \frac{\partial B}{\partial t} = 0$ - Faraday law of EMF

III $\nabla \cdot E = 4\pi q$ - Coulomb law: "E-source" = "charge"

IV $\nabla \times B - \frac{1}{c} \frac{\partial E}{\partial t} = \frac{4\pi}{c} j$ - Ampere law: B produced by current

Taking div of eq-n IV we get

"charge conservation" law: $Dt(q) = -\text{div}(j)$ $c = \text{light speed}$

Potentials: (I) $\Rightarrow B = \nabla \times A$ (II) $\Rightarrow E = -\frac{1}{c} A_t - \nabla \phi$
↑ vector ↑ scalar

Gauge transform:

$$A \rightarrow A + \nabla \chi$$

$$\phi \rightarrow \phi - \frac{1}{c} \chi_t$$

Adjust χ ?

Lorentz gauge: $\nabla \cdot A + \frac{1}{c} \phi_t = 0$

$$\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right) \chi = \dots$$

$$\Rightarrow \text{III} \quad \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right) \phi = 4\pi q$$

$$\text{IV} \quad \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right) A = \frac{4\pi}{c} j$$

\Rightarrow Wave eq-n with speed c

(II) Medium: $(E, B) \rightarrow (D, H)$ new fields

Constitutive relations: $D = \epsilon E$; $H = \frac{1}{\mu} B$ w/o polarization
↑ dielectric ↑ magnetic permeabil.

$$\Rightarrow \left\{ \begin{array}{l} \nabla \cdot B = 0 \\ \nabla \times E + \frac{1}{c} \frac{\partial B}{\partial t} = 0 \\ \nabla \cdot D = 4\pi q \\ \nabla \times H - \frac{1}{c} \frac{\partial E}{\partial t} = \frac{4\pi}{c} j \end{array} \right\}$$

\rightarrow potentials (A, ϕ)

$$\left(\epsilon \mu \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \begin{pmatrix} \phi \\ A \end{pmatrix} = \begin{pmatrix} q \\ j \end{pmatrix}$$

Wave eq-n with speed $c' = \frac{1}{\sqrt{\mu \epsilon}} \leq c$