

M224:

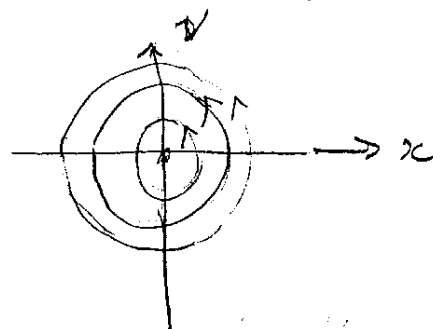
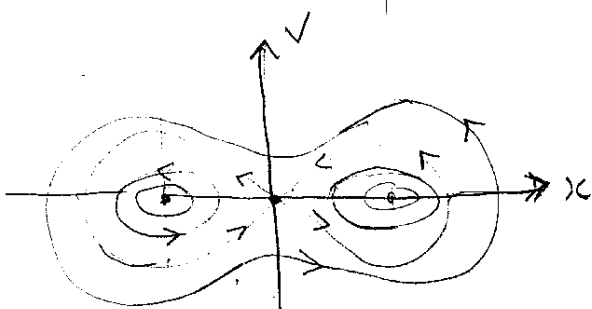
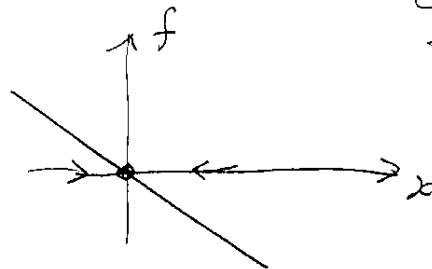
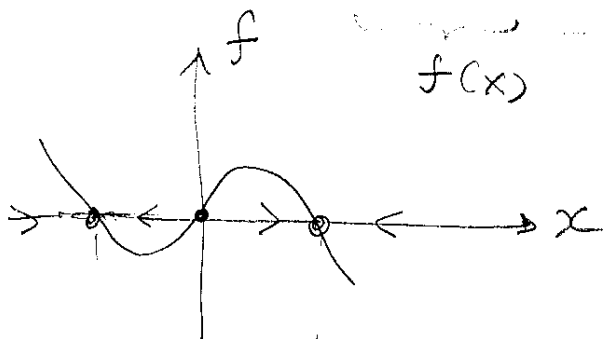
# Oscillators

Duffing:

$$\begin{cases} \dot{x} = v \\ \dot{v} = ax - bx^3 \end{cases} \quad \text{Lin. ose:}$$

Lin. ose:

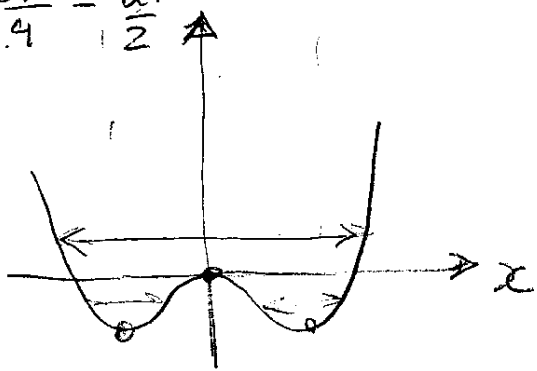
$$\begin{cases} \dot{x} = v \\ \dot{v} = -kx \end{cases}$$



Potential  $V$ :

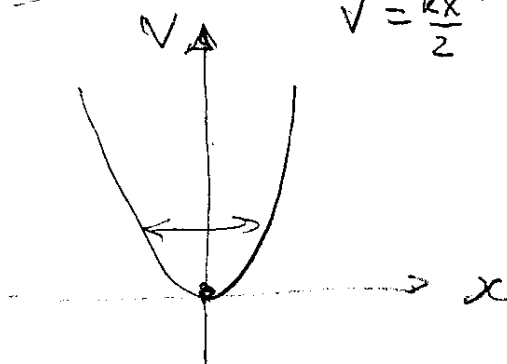
$$f(x) = -V'(x)$$

$$V = \frac{bx^4}{4} - \frac{ax^2}{2}$$



double well

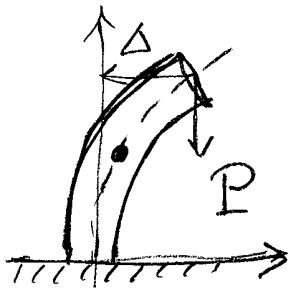
$$V = \frac{kx^2}{2}$$



single well

## Swaying sly scraper (P-delta)

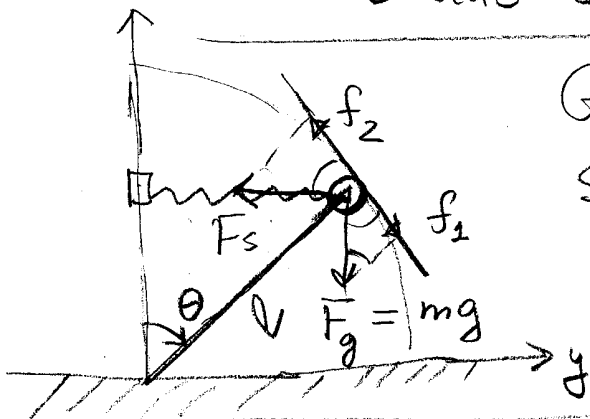
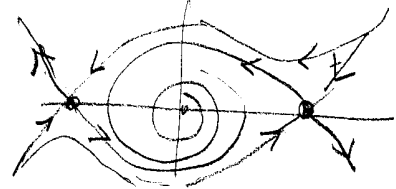
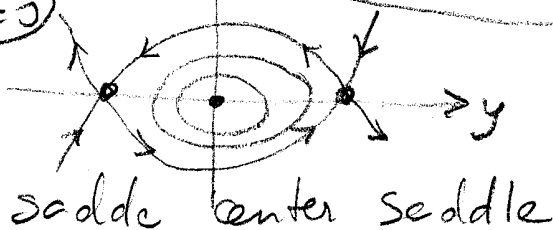
## and spring-pendulum



⇒ Approximate eq-n:

$$\ddot{y} = -\underbrace{ay}_{(P-\Delta) \text{ force}} + \underbrace{by^3}_{\text{force}} - \underbrace{\alpha \dot{y}}_{\text{damping}}$$

$\alpha = 0$



Gravity:  $F_g = mg$

Spring:  $F_s = -ky$

Projections:  $f_1 = F_g \sin \theta = mg \sin \theta$   
 $f_2 = F_s \cos \theta = kl \sin \cos$

$$(1) \quad m l \ddot{\theta} = (-kl \cos \theta + mg) \sin \theta - \alpha \dot{\theta}$$

Cubic approximation:  $\cos \theta = 1 - \frac{\theta^2}{2} + \dots$ ;  $\sin \theta = \theta - \frac{\theta^3}{6} + \dots$

$$(2) \quad \ddot{\theta} = \left[ \left( \frac{g}{l} - \frac{k}{m} \right) + \frac{k}{2m} \theta^2 \right] \theta$$

Problem 2: (i) Derive cubic approximation (2) of (1)

(ii) Find equilibria, sketch phase plane and solution curves in 2 cases:  $\frac{k}{m} > g/l$ ;  $\frac{k}{m} < g/l$

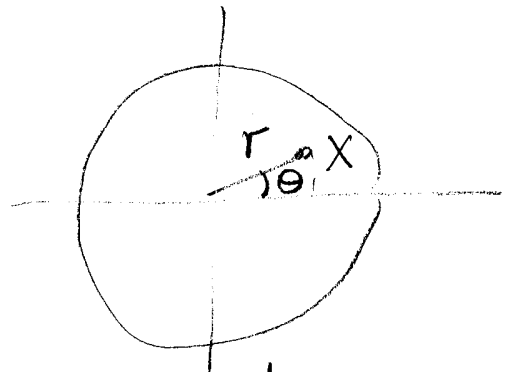
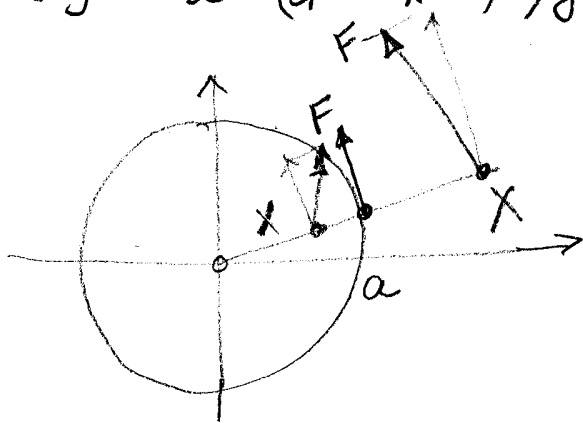
(iii) Discuss stability of equilibria in both cases.

Limit cycle.

V. field

$$1) \begin{cases} \dot{x} = -y + (a^2 - x^2 - y^2)x \\ \dot{y} = x + (a^2 - x^2 - y^2)y \end{cases}$$

$$F(x) = x^\perp + (a^2 - r^2)X$$

Analytic solution in polar coord.Polar change of variables:  $\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$ 

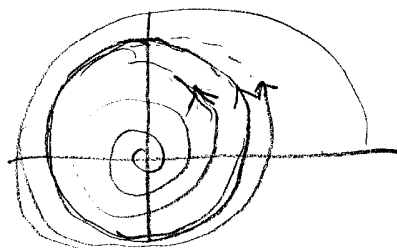
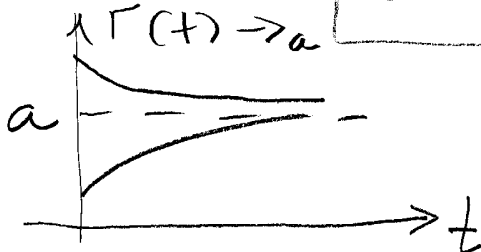
$$\Rightarrow \begin{cases} \dot{r} = r(a^2 - r^2) \\ \dot{\theta} = 1 \end{cases} \leftarrow \text{decoupled}$$

$$(i) \int_{r_0}^r \frac{dr}{r(a^2 - r^2)} = t \Rightarrow r(t) = a \frac{r_0 e^{a^2 t}}{\sqrt{(a^2 - r_0^2) + r_0^2 e^{2a^2 t}}}$$

$$(ii) \theta = t + \theta_0$$

 $\Rightarrow$ 

$$\begin{cases} x(t) = r(t) \cos(t + \theta_0) \\ y(t) = r(t) \sin(t + \theta_0) \end{cases}$$



Limit cycle  
 $r = a$   
 + spirals