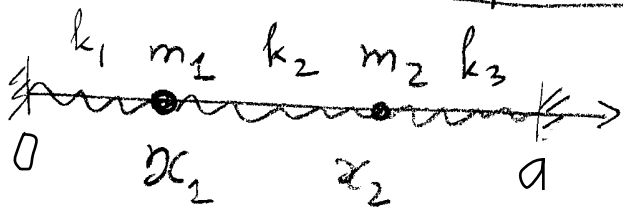


Coupled oscillators



$$\begin{cases} m_1 \ddot{x}_1 = -(k_1 + k_2)x_1 + k_2 x_2 \\ m_2 \ddot{x}_2 = k_2 x_1 - (k_2 + k_3)x_2 + k_3 a \end{cases}$$

$$\ddot{\underline{x}} = - \underbrace{\begin{bmatrix} \frac{k_1+k_2}{m_1} & -\frac{k_2}{m_2} \\ -\frac{k_2}{m_2} & \frac{k_2+k_3}{m_2} \end{bmatrix}}_A \underline{x} + \begin{pmatrix} 0 \\ F \end{pmatrix} \quad - \quad 2^{\text{nd}} \text{ order ODS}$$

Eigenvalue problem for A: $\begin{array}{c|c} \lambda_1 & \lambda_2 \\ \hline X_1 & X_2 \end{array}$

Always: $0 < \lambda_1 < \lambda_2$; $X_1 = \begin{pmatrix} + \\ + \end{pmatrix}$; $X_2 = \begin{pmatrix} + \\ - \end{pmatrix}$

Example: $\begin{cases} k_1 = k_2 = k_3 = k \\ m_1 = m_2 = m \end{cases} \Rightarrow A = \frac{k}{m} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$

Eigens: $\begin{array}{c|c} 1 & 3 \\ \hline \begin{pmatrix} 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 1 \\ -1 \end{pmatrix} \end{array}$

$A_1 \cos(\omega_1 t - \phi_1)$

GS: $\underline{x}(t) = (c_1 \cos \sqrt{\lambda_1} t + c_2 \sin \sqrt{\lambda_1} t) X_1 +$

Frequencies: $\omega_i = \sqrt{\lambda_i}$ $+ (c_3 \cos \sqrt{\lambda_2} t + c_4 \sin \sqrt{\lambda_2} t) X_2$

Example: $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = A_1 \cos(\omega_1 t - \phi_1) \begin{pmatrix} 1 \\ 1 \end{pmatrix} + A_2 \cos(\omega_2 t - \phi_2) \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

ω_1

X_1 -pattern

ω_2

X_2 -pattern

Problems:

(2)

- 1) Find an equilibrium position (x_1^0, x_2^0) for coupled oscillator
- (i) in general case $k_1, k_2, k_3, m_1, m_2, a$
 - (ii) for $k_1 = k_3 = 1, k_2 = 2; m_1 = 2, m_2 = 1, a = 5$

- 2) Compute general oscillating solution in case 1(ii), and IVP solution

for
$$\begin{cases} x_1(0) = 0 \\ x_2(0) = 4 \end{cases} \quad \begin{cases} \dot{x}_1 = 0 \\ \dot{x}_2 = 0 \end{cases}$$

Plot it.