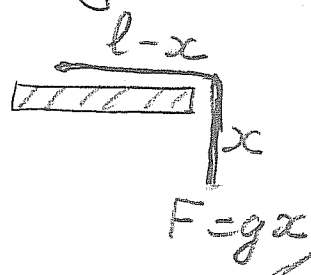


Applications of LDS

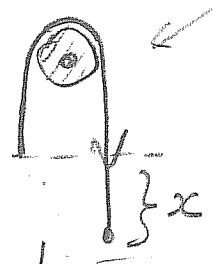
Examples:

1. Sliding chain.



$$l\ddot{x} = gx$$

Cable over frictionless peg



Chain on cog wheel

$$\left(l + \frac{m}{2}\right)\ddot{x} = gl$$

$m = \text{mass wheel}$

DS

$$\begin{cases} \dot{x} = v \\ \dot{v} = \frac{g}{l}v \end{cases}$$

$$A = \begin{bmatrix} 0 & 1 \\ g/l & 0 \end{bmatrix} \Rightarrow \alpha = \sqrt{g/l}$$

$$\begin{pmatrix} 1 \\ \alpha \end{pmatrix} \mid \begin{pmatrix} 1 \\ -\alpha \end{pmatrix} \Rightarrow$$

$$x(t) = c_1 e^{\alpha t} \begin{pmatrix} 1 \\ \alpha \end{pmatrix} + c_2 e^{-\alpha t} \begin{pmatrix} 1 \\ -\alpha \end{pmatrix}$$

For IVP: $\begin{cases} x(0) = b > 0 \\ v(0) = 0 \end{cases} \Rightarrow x(t) = \frac{b}{2} [e^{\alpha t} \begin{pmatrix} 1 \\ \alpha \end{pmatrix} + e^{-\alpha t} \begin{pmatrix} 1 \\ -\alpha \end{pmatrix}]$

$$x(t) = \frac{b}{2} (e^{\alpha t} + e^{-\alpha t}) = b \cosh \alpha t$$

Sliding time: $x(t_s) = l \Rightarrow t_s = \cosh^{-1}(l/b) = \frac{1}{\alpha} \ln\left(\frac{l + \sqrt{l^2 - b^2}}{b}\right)$

Problem 1: i) Solve sliding chain problem for IV

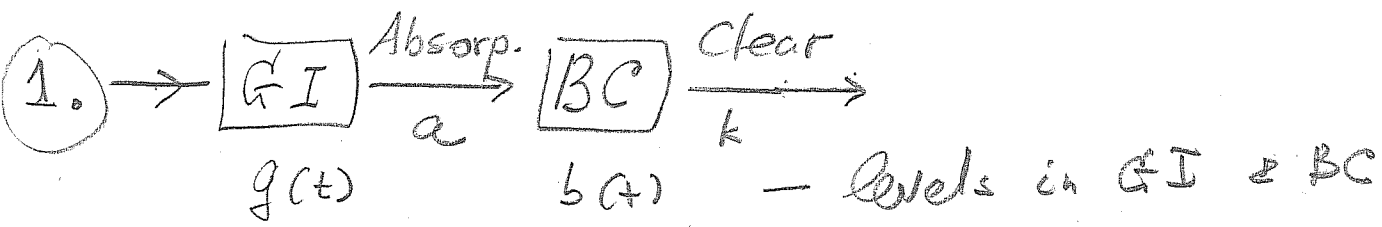
$x(0) = 0; v(0) = v_0 = 0$. Find sliding time t_s .

ii) Compute solution & t_s for $l = 5m; v_0 = .5 m/s$

($g = 10 m/s^2$)

Transport (drug delivery)

(2)



LDS $\left\{ \begin{array}{l} \dot{g} = -a g \\ \dot{b} = a g - k b \end{array} \right. \mid g(0) = g_0 - \text{Dose}$

$A = \begin{bmatrix} -a & 0 \\ a & -k \end{bmatrix}$

$\begin{array}{c|c} -a & -k \\ \hline (k-a) & (0) \end{array}$

Direct: $g(t) = g_0 e^{-at}$

$b(t) = \frac{a}{k-a} (e^{-at} - e^{-kt}) g_0$ (1)

Problem 2: i) show that maximal b-level

$b_{\max} = (a-1) \alpha^{\frac{1}{1-\alpha}} g_0$ ($\alpha = \frac{k}{a}$) at $t_{\max} = \frac{1}{k-a} \ln \frac{k}{a}$.

ii) Compute & plot solution $b(t)$ for $a = .02/\text{min}$
 $k = .05/\text{min}$.

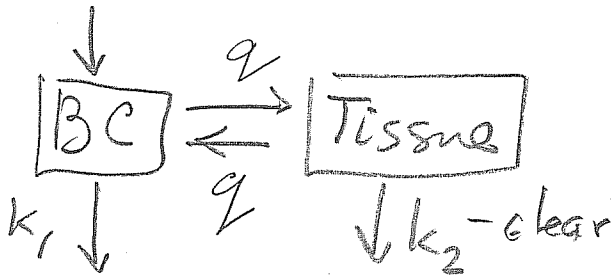
iii) Find dose d_0 required to get

$b_{\max} > 5 \text{ mg}$

Hint: change variable $t \rightarrow u = e^{-at}$ in (1)

② IV drug:

③



Volumes: V_1 (BC)

V_2 (Tis)

Concentrations: $x(t)$ - BC

$y(t)$ - Tis

$$2) \begin{cases} V_1 \dot{x} = q(y-x) - k_1 x \\ V_2 \dot{y} = q(x-y) - k_2 y \end{cases} \quad \begin{array}{l} x(0) = D_0 - \text{dose} \\ y(0) = 0 \end{array}$$

Problem 3: Solve (2) for $V_1 = 3L; V_2 = 2L$

$q = 0.5 \text{ L/min}; k_1 = 0.05/\text{min}; k_2 = 0.03/\text{min}$

Prot $\{x(t), y(t)\}$ Find y_{\max} .

Bug flight

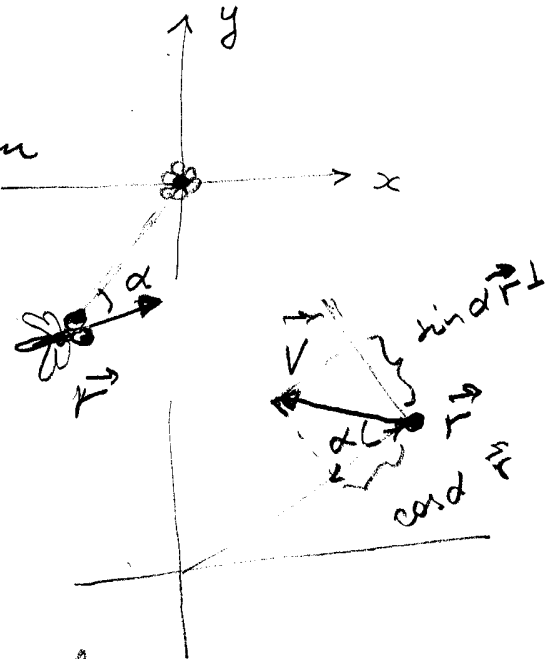
Bug's eye is fixed on object
at a fixed angle $0 < \alpha < \pi/2$
So velocity at any position

$\vec{r} = (x, y)$ is given by

$$\vec{V}(\vec{r}) = \frac{V_0}{r} (-\cos \alpha \vec{r} + \sin \alpha \vec{r}^\perp)$$

Here V_0 - const speed; $r = |\vec{r}|$

$\vec{r}^\perp = (-y, x)$ - perpendicular vector.



The eq-ns of motion: $\dot{\vec{r}} = \vec{V}(\vec{r})$

turns into ODS

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \frac{V_0}{\sqrt{x^2 + y^2}} \begin{bmatrix} -\cos \alpha & -\sin \alpha \\ \sin \alpha & -\cos \alpha \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

Scalar factor $\frac{V_0}{r}$ does not affect trajectories,
given by the linear ODS with matrix

$$A = \begin{bmatrix} -c_\alpha & -s_\alpha \\ s_\alpha & -c_\alpha \end{bmatrix} \Rightarrow \text{complex eigenvalues}$$

$$\lambda_{1,2} = -c_\alpha \pm i s_\alpha \Rightarrow \text{spiral sink}$$

